

Ancillary Material #2 Solutions

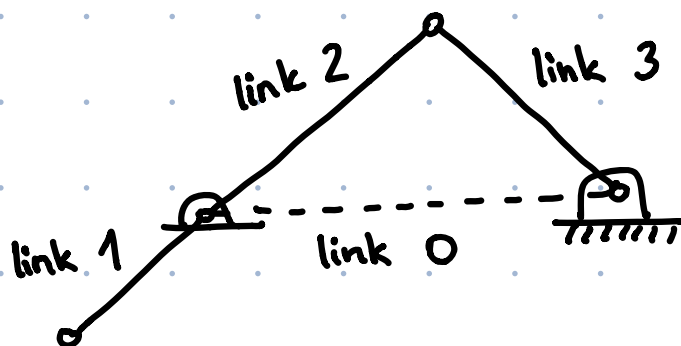
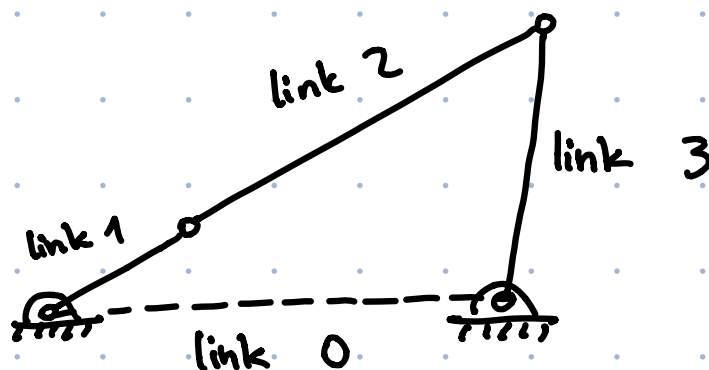
- (1) (a) (i) $3.5 < 3.25 + 1.5 + 1$, so it is a mechanism.
(ii) $2.5 < 2.5 + 1 + 2$, so it is a mechanism.

(b) (i) $l_{\max} + l_{\min} < l_a + l_b$ and since $l_o = l_{\min}$, it is a drag-link mechanism.

(ii) $l_{\max} + l_{\min} < l_a + l_b$, and since $l_a = l_{\min}$, it is a crank-rocker mechanism.

(c) (i) No limiting position.

(ii)



$$(2) \quad \begin{aligned} (3) \quad x_0 &= x_1 + y_1 + 3z_1 \\ y_0 &= 2x_1 - y_1 + 4z_1 \\ z_0 &= 3x_1 + 5z_1 \end{aligned}$$

We want to find a matrix $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ or $T \in \mathbb{R}^{3 \times 3}$ such that whenever a vector v is expressed in Σ_0 , Tv gives the expression of v in Σ_1 , i.e.,

$$v^1 = Tv^0.$$

Let us consider the following vectors expressed in Σ_1 :

$$v_1 = \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix}, \quad v_2 = \begin{bmatrix} 2 \\ -1 \\ 4 \end{bmatrix}, \quad v_3 = \begin{bmatrix} 3 \\ 0 \\ 5 \end{bmatrix}.$$

When these vectors are expressed in Σ_0 , they are respectively e_1, e_2, e_3 ; the standard unit vectors, i.e.,

$$T^{-1} \begin{pmatrix} 1 \\ 1 \\ 3 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}; \quad T^{-1} \begin{pmatrix} 2 \\ -1 \\ 4 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}; \quad T^{-1} \begin{pmatrix} 3 \\ 0 \\ 5 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

Written another way, these equations tell us,

$$T^{-1} \begin{bmatrix} 1 & 2 & 3 \\ 1 & -1 & 0 \\ 3 & 4 & 5 \end{bmatrix} = I \Rightarrow T = \begin{bmatrix} 1 & 2 & 3 \\ 1 & -1 & 0 \\ 3 & 4 & 5 \end{bmatrix}$$

(b) T takes vectors expressed in Σ_0 to Σ_1 .

Hence T^{-1} takes vectors expressed in Σ_1 to Σ_0 .

We want to compute $T^{-1}\omega$. To do this, we need to compute T^{-1} :

$$\left[\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 1 & -1 & 0 & 0 & 1 & 0 \\ 3 & 4 & 5 & 0 & 0 & 1 \end{array} \right] \rightarrow \left[\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & -3 & -3 & -1 & 1 & 0 \\ 0 & -2 & -4 & -3 & 0 & 1 \end{array} \right]$$

$$\rightarrow \left(\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1/3 & -1/3 & 0 \\ 0 & 1 & 2 & 3/2 & 0 & -1/2 \end{array} \right)$$

$$\rightarrow \left(\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1/3 & -1/3 & 0 \\ 0 & 0 & 1 & 7/6 & 1/3 & -1/2 \end{array} \right)$$

$$\rightarrow \left(\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & 0 & -5/6 & -2/3 & 1/2 \\ 0 & 0 & 1 & 7/6 & 1/3 & -1/2 \end{array} \right)$$

$$\rightarrow \left(\begin{array}{ccc|ccc} 1 & 2 & 0 & -5/2 & -1 & 3/2 \\ 0 & 1 & 0 & -5/6 & -2/3 & 1/2 \\ 0 & 0 & 1 & 7/6 & 1/3 & -1/2 \end{array} \right)$$

$$\left(\begin{array}{ccc|ccc} 1 & 0 & 0 & -5/6 & 1/3 & 1/2 \end{array} \right)$$

$$\rightarrow \left(\begin{array}{ccc|ccc} 0 & 1 & 0 & -5/6 & -2/3 & 1/2 \\ 0 & 0 & 1 & 7/6 & 1/3 & -1/2 \end{array} \right)$$

$$\text{Therefore, } T^{-1} = \frac{1}{6} \begin{bmatrix} -5 & 2 & 3 \\ -5 & -4 & 3 \\ 7 & 2 & -3 \end{bmatrix}$$

Hence

$$\begin{aligned} T^{-1} \omega &= \frac{1}{6} \begin{bmatrix} -5 & 2 & 3 \\ -5 & -4 & 3 \\ 7 & 2 & -3 \end{bmatrix} \begin{bmatrix} -1 \\ 2 \\ 3 \end{bmatrix} \\ &= \frac{1}{6} \left(\begin{bmatrix} 5 \\ 5 \\ -7 \end{bmatrix} + \begin{bmatrix} 4 \\ -8 \\ 4 \end{bmatrix} + \begin{bmatrix} 9 \\ 9 \\ -9 \end{bmatrix} \right) = \begin{bmatrix} 3 \\ 1 \\ -2 \end{bmatrix} \end{aligned}$$

$$(3) (a) \frac{v}{\|v\|} = \frac{(18 \ -11 \ 7)^T}{\sqrt{324+121+49}} = \begin{pmatrix} 0.810 \\ -0.495 \\ 0.315 \end{pmatrix}$$

$$(b) \cos(\theta) = \frac{v \cdot w}{\|v\| \|w\|} = -0.12806 \Rightarrow \theta = 1.699 \approx 97.36^\circ$$

$$(c) v \times w = \begin{pmatrix} -5 \\ -5 \\ -1 \end{pmatrix}$$

$$\frac{v \times w}{\|v \times w\|} = \frac{(5 \ 5 \ 1)^T}{\sqrt{51}}$$

$$(d) \text{ Consider the matrix } A = \begin{bmatrix} -5 & 25/9 & -185/9 \\ 5/9 & 5/3 & 5 \\ -35/9 & -5/9 & -115/9 \end{bmatrix} = \frac{1}{9} \begin{bmatrix} -45 & 25 & -185 \\ 5 & 15 & 45 \\ -35 & -5 & -115 \end{bmatrix}$$

$$= \frac{5}{9} \begin{bmatrix} -9 & 5 & -37 \\ 1 & 3 & 9 \\ -7 & -1 & -23 \end{bmatrix}$$

$$\det(A) = \frac{125}{729} \left(-9 \cdot \begin{vmatrix} 3 & 9 \\ -1 & -23 \end{vmatrix} - \begin{vmatrix} 5 & -37 \\ -1 & -23 \end{vmatrix} - 7 \begin{vmatrix} 5 & -37 \\ 3 & 9 \end{vmatrix} \right) \\ = \frac{125}{729} (540 + 152 - 1092) \approx -68.59 \neq 0.$$

$$(4) \quad \langle f_i, f_j \rangle = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases} = \delta_j^i.$$

Let us study the inner product on $\mathbb{R}[x]_2$.

An arbitrary element of $\mathbb{R}[x]_2$ has the form:

$$p(x) = \alpha_0 + \alpha_1 x + \alpha_2 x^2.$$

Thus, if $q(x) \in \mathbb{R}[x]_2$ s.t. $q(x) = \beta_0 + \beta_1 x + \beta_2 x^2$, then, we have

$$\begin{aligned} \langle p, q \rangle &= \int_0^1 (\alpha_0 + \alpha_1 x + \alpha_2 x^2)(\beta_0 + \beta_1 x + \beta_2 x^2) dx \\ &= \int_0^1 \left\{ \alpha_0 \beta_0 + (\alpha_0 \beta_1 + \alpha_1 \beta_0)x + (\alpha_0 \beta_2 + \alpha_1 \beta_1 + \alpha_2 \beta_0)x^2 \right. \\ &\quad \left. + (\alpha_1 \beta_2 + \alpha_2 \beta_1)x^3 + \alpha_2 \beta_2 x^4 \right\} dx \\ &= \alpha_0 \beta_0 + \frac{1}{2}(\alpha_0 \beta_1 + \alpha_1 \beta_0) + \frac{1}{3}(\alpha_0 \beta_2 + \alpha_1 \beta_1 + \alpha_2 \beta_0) \\ &\quad + \frac{1}{4}(\alpha_1 \beta_2 + \alpha_2 \beta_1) + \frac{1}{5} \alpha_2 \beta_2. \quad (*) \end{aligned}$$

Thus, if we represent the polynomials p, q in the basis $\{1, x, x^2\}$ for $\mathbb{R}[x]_2$ by $\bar{p}$ and $\bar{q}$, we can express the inner product $\langle p, q \rangle$ by

$$\langle p, q \rangle = \bar{p}^T M \bar{q}, \text{ where, } M \text{ can be read off from } (*) \text{ as}$$

$$M = \begin{bmatrix} 1 & 1/2 & 1/3 \\ 1/2 & 1/3 & 1/4 \\ 1/3 & 1/4 & 1/5 \end{bmatrix}$$

Now, let's apply the constraints for f_3 . We have $\langle f_1, f_3 \rangle = \langle f_2, f_3 \rangle = 0$ and $\langle f_3, f_3 \rangle = 1$.

Let $f_3(x) = \alpha_0 + \alpha_1 x + \alpha_2 x^2$. Then

$$0 = \langle f_1, f_3 \rangle = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}^T M \begin{pmatrix} \alpha_0 \\ \alpha_1 \\ \alpha_2 \end{pmatrix} = \alpha_0 + \frac{1}{2} \alpha_1 + \frac{1}{3} \alpha_2.$$

$$0 = \langle f_2, f_3 \rangle = \begin{pmatrix} \sqrt{3} \\ -2\sqrt{3} \\ 0 \end{pmatrix}^T M \begin{pmatrix} \alpha_0 \\ \alpha_1 \\ \alpha_2 \end{pmatrix} = \sqrt{3} \alpha_0 + \frac{\sqrt{3}}{2} \alpha_1 + \frac{\sqrt{3}}{3} \alpha_2 \\ -\sqrt{3} \alpha_0 - \frac{2\sqrt{3}}{3} \alpha_1 - \frac{\sqrt{3}}{2} \alpha_2$$

$$= -\frac{\sqrt{3}}{6} (\alpha_1 + \alpha_2)$$

$$1 = \langle f_3, f_3 \rangle = \alpha_0^2 + \alpha_0 \alpha_1 + \frac{1}{3} (2\alpha_0 \alpha_2 + \alpha_1^2) + \frac{1}{2} \alpha_1 \alpha_2 + \frac{1}{5} \alpha_2^2$$

Hence, we get the system of polynomial equations to solve for $\alpha_0, \alpha_1, \alpha_2$: $[\alpha_1 = -\alpha_2]$

$$\alpha_0 + \frac{1}{6} \alpha_1 = 0$$

$$\alpha_0^2 + \alpha_0 \alpha_1 + \frac{1}{3} (-2\alpha_0 \alpha_1 + \alpha_1^2) - \frac{1}{2} \alpha_1^2 + \frac{1}{5} \alpha_1^2 \\ - \frac{3}{10} \alpha_1^2$$

$$= \alpha_0^2 + \frac{1}{3} \alpha_0 \alpha_1 + \frac{1}{30} \alpha_1^2 = 1.$$

Substituting from the top to the bottom:

$$1 = \alpha_0^2 - 2\alpha_0^2 + \frac{6}{5} \alpha_0^2 \Rightarrow \alpha_0 = \pm \sqrt{5}; \quad \alpha_1 = \mp 6\sqrt{5}; \quad \alpha_2 = \pm 6\sqrt{5}$$