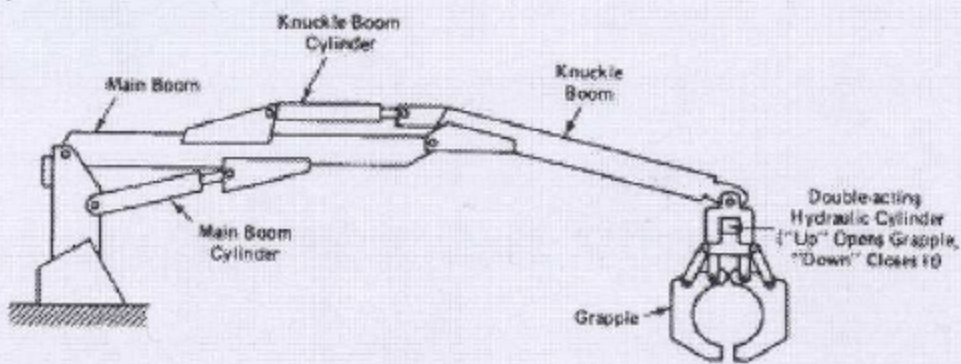


Question 1: Determine the number of degrees of freedom of the following mechanisms using Gruebler's equation.

a) **solution 1a)**



- 13 links
- 13 revolute
- 3 prismatic

$$F = 3(n-1) - 2f$$

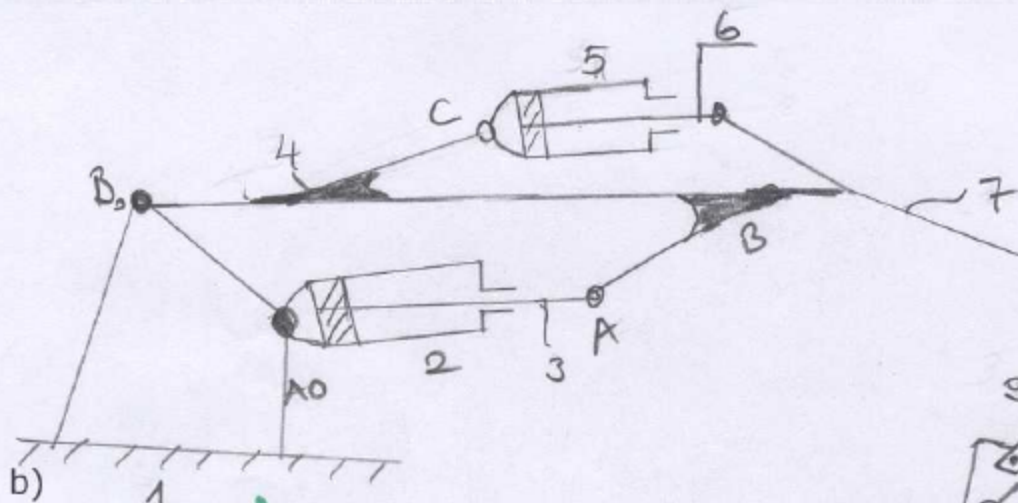
$\downarrow$
 revolute

$\downarrow$
 phanote

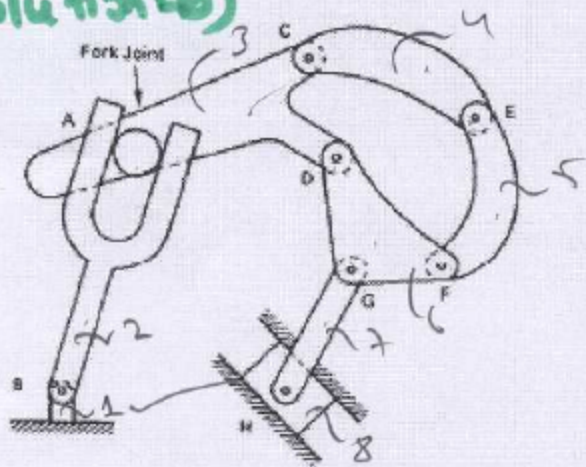
$$F = 3(13-1) - 2(13) - 2(3)$$

$$F = 36 - 32$$

$$f = 4$$



b) ¹
solution (b)



- 8 links
- 7 revolute
- 1 prismatic (of joint)
- 1 pin insolt (2 dof joint)

$$f = 3(n-1) - 2f_1 - f_2$$

$$F = 3(8-1) - 2(7) - 2(1) - 1(1)$$

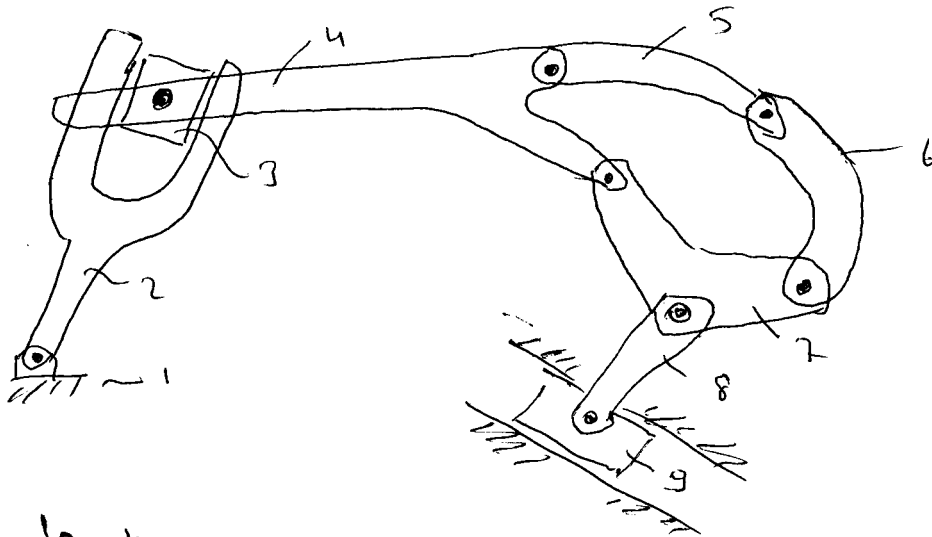
$\downarrow$ revolute $\downarrow$ prismatic $\downarrow$ pinning slot

$$F = 21 - 14 - 2 - 1$$

$$F = 21 - 17 = 4 \text{ dof}$$

1) b) Alternative solution

As suggested in Erdman pages 27-28, due to kinematic equivalence "pin-in-slot" joint can be replaced by two lower pair joints (2 revolute and 2 prismatic joints) and 2 link.



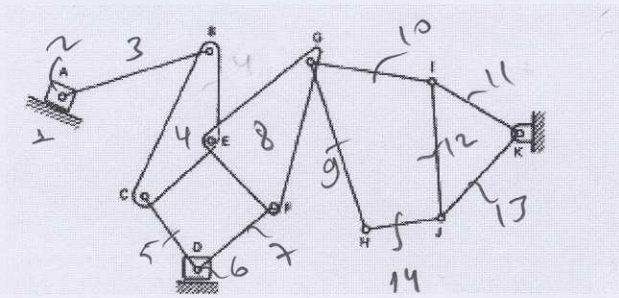
In this case

- $n = 9$ links
- 8 revolute joints
- 2 prismatic joints

$$\begin{aligned} F &= 3(n-1) - 2f_1 \\ &= 3(9-1) - 2(8) - 2(2) \\ &= 24 - 16 - 4 = 4 \text{ dof} \end{aligned}$$



c) -solution(c)



- 14 links
- 16 revolute
- 2 prismatic

$$F = 3(h-1) - 2f_1 - f_2$$

$$F = 3(14-1) - 2(13) - 2(2)$$

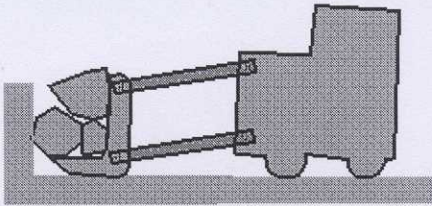
$$F = 39 - 36$$

$$F = 3$$

Question 2: Identify the type of linkages (four-bar, slider-crank, etc.) for the following mechanisms.

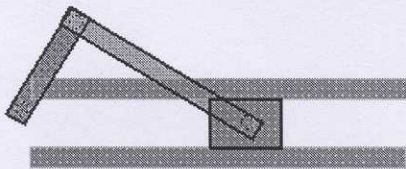
Solutions 2.)

a)



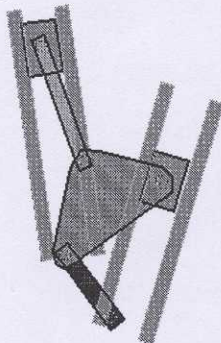
→ A (parallel) four bar linkage,

b)



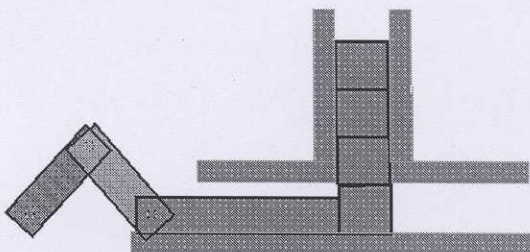
→ A slider-crank mechanism.

c)



→ A slider-crank mechanism with multiple sliders.

d)



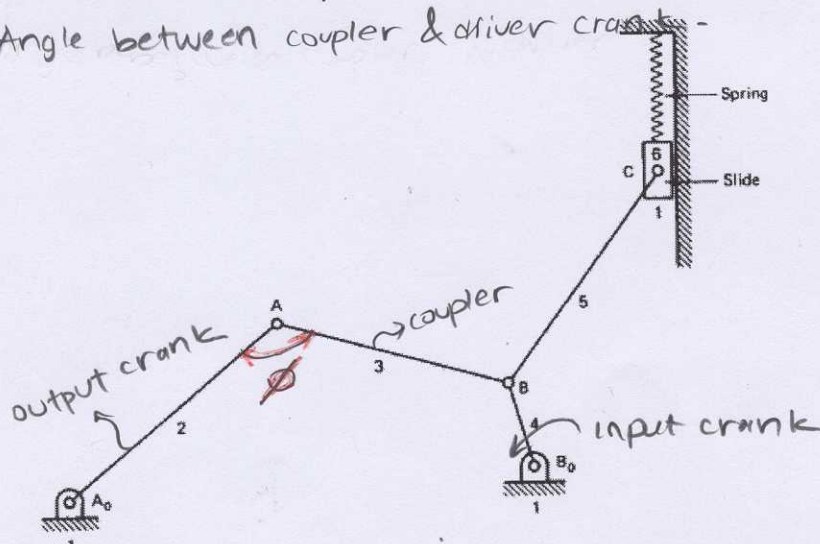
→ A slider-crank mechanism

Question 3: Determine the transmission angles for the following mechanisms:

- a) 6-bar mechanism where link 6 is the input and link 2 is the output.

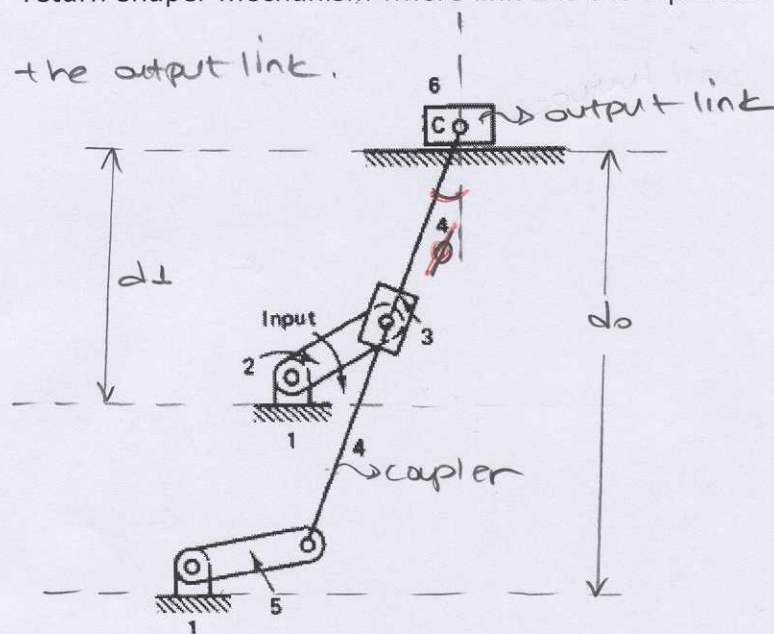
Solution 3a)

Transmission angle: Angle between coupler & driver crank

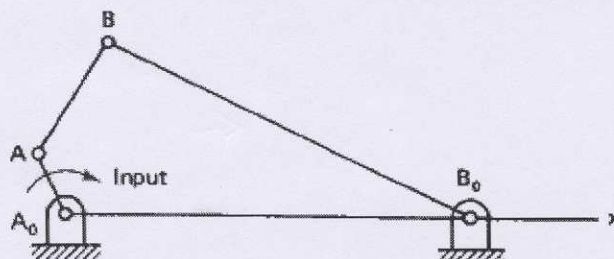


- b) The two quick-return shaper mechanism where link 2 is the input and link 6 is the output.

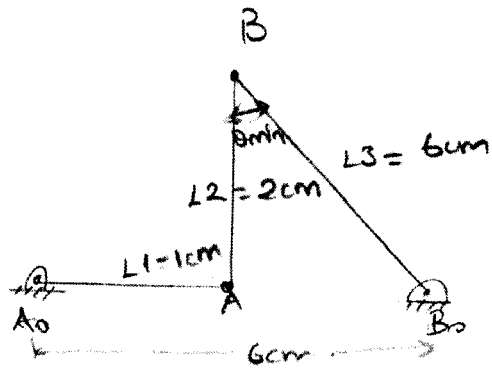
Solution 3b) Link 6 is the output link.



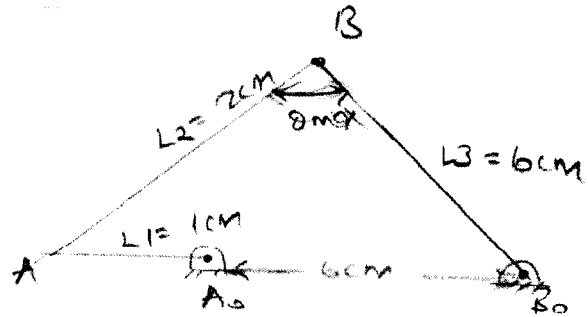
- c) Determine the maximum and minimum transmission angles for the following four-bar linkage with dimensions: $A_0B_0 = 6$ cm, $A_0A = 1$ cm, $AB = 2$ cm, $BB_0 = 6$ cm.



Solution 3c)



Minimum value of transmission angle



Maximum value of transmission angle

$$A_0B_0 = 6\text{cm}$$

$$A_0A = 1\text{cm}$$

$$AB = 2\text{cm}$$

$$BB_0 = 6\text{cm}$$

For min. transmission angle:

$$\cos \phi_{\min} = \frac{(AB)^2 + (BB_0)^2 - (A_0B_0)^2}{2(AB)(BB_0)} = \frac{2^2 + 6^2 - 6^2}{2 \cdot 2 \cdot 6} = \frac{4 + 36 - 36}{24} = \frac{4}{24} = \frac{1}{6}$$

$$\phi_{\min} = \arccos\left(\frac{1}{6}\right) = 0.9857 \text{ rad}$$

$$\phi_{\min} = 56.3128^\circ$$

For max. transmission angle:

$$\cos \phi_{\max} = \frac{(AB)^2 + (BB_0)^2 - (A_0B_0)^2}{2(AB)(BB_0)} = \frac{2^2 + 6^2 - 7^2}{2 \cdot 2 \cdot 6} = \frac{4 + 36 - 49}{24} = \frac{-9}{24} = -\frac{3}{8}$$

$$\phi_{\max} = \arccos\left(-\frac{3}{8}\right) = 1.95 \text{ rad}$$

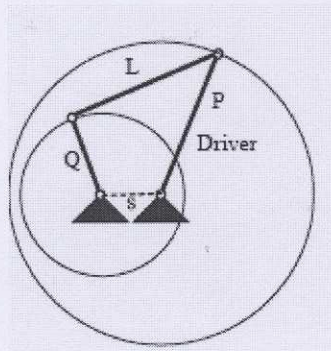
$$\phi_{\max} = 112^\circ$$

Question 4: Classify the following four-bar linkages according to Grashof criterion.

a) **solution 4)**

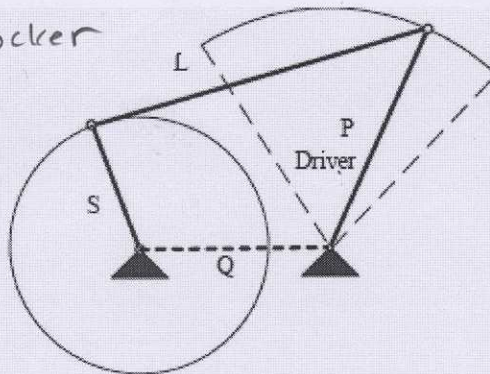
$$L + S < P + Q$$

This is a drag link
since shortest link is
the ground link(s)



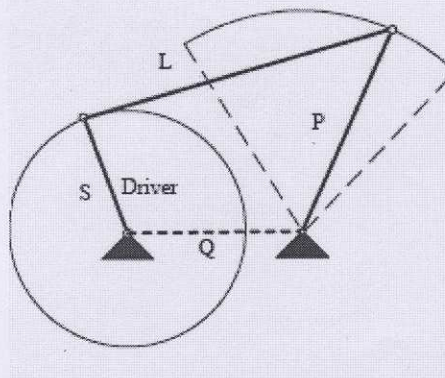
b) $L + S < P + Q$

This is a crank-rocker
since shortest link
is the output link(s).



c) $L + S < P + Q$

This is a crank rocker
since shortest link is
the output link(s).



d) $L + S < P + Q$

This is a double rocker
since shortest link is the
coupler.

